



Impact of High PV Penetration on Transient Stability — a Case Study on the U.S. ERCOT System

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Abstract. This study was performed to assess the impact of high photovoltaic (PV) penetration on transient stability using a series of hypothetical models of the ERCOT system. This was done by calculating the critical clearing time (CCT) when faulting various busses. Varying levels of PV penetration were used to study the system transient stability. For each case 15% wind penetration was also included.

It was found that under the PV volt/Var control with plant-level GE SolarControl settings, PV penetration at lower level can slightly improve the transient stability in the ERCOT system model. However, at approximately 54% penetration of renewables (39% PV and 15% wind), transient stability starts to show declining trend. This value has slight variance depending on PV distribution.

Key words. Transient stability, renewables, photovoltaic penetration.

1. Introduction

The influence of increasing renewable generation on power system stability has been the focus of recent years. For example, recent studies found that network-fault-induced wind turbine active power dips potentially represent a fundamental change in frequency stability risk [1]. Similar to wind power, the penetration of PV is increasing in many power systems due to concerns on environments and climate change. PV power plants have many unique physical features compared with conventional power plants and wind power generators. The increasing penetration of PV is changing many aspects on power system planning and operation.

Transient stability focuses on the capability of the system to keep synchronism under various disturbances in power systems. Typical theoretical study and demonstration on transient stability is usually based on a single machine and infinite bus system. Factors that influence transient stability include the generator loading condition, generator output during the fault, fault-clearing time, the infinite bus voltage magnitude (point of connection voltage magnitude), and

etc. The dominant method for transient stability analysis for multi-machine power systems is time domain simulation based on numerical integration on differential equations and solving algebraic equations [2].

Some studies have already started to investigate the impact of PV on transient stability. Ref. [3] conducted a study on the WECC system and found that PV can have both detrimental and beneficial impact on the transient stability. The beneficial impact is generally associated with the fact that increased PV penetration usually represents more distributed generation, thus losing one transmission component will be less likely to lead to severe consequences. The detrimental impact comes from high PV penetration usually resulting in larger voltage perturbation.

Ref. [4] studied the system transient stability by integrating PV generation to the New England test system. It found that the PV power plants could significantly change the voltage profile after disturbance and make the system more vulnerable to stability problems. Ref. [5] studied the impact of PV on the IEEE-39 bus system when PV plants operate at unity power factor (zero reactive power output). Its simulation results showed that the higher PV penetration will impair the transient stability of the study system. Also based on the IEEE-39 bus system, the study in Ref. [6] found that if PV plants can provide voltage control during disturbance, voltage recovery during faults can be improved, thus enhancing transient stability. It is also demonstrated that under-voltage disconnection of PV can be detrimental to system stability since it will result in more significant excursions after disturbances.

The study in [7] investigated the stability of the Ontario system with large-scale PV under various scenarios, namely distributed units, centralized farms with and without voltage control capabilities. The result showed that the centralized PV farms working in voltage control or unity power factor mode, which are modeled as PV or

PQ generators, have no major impact on the system transient stability. On the other hand, the distribution PV units, which are modelled as negative PQ loads, can significantly improve the voltage and transient stability. The underlying main reason of this improvement is that the increase of distributed PV corresponds to the reduction of load, thus improving transient stability metrics such as the critical clearing time. Ref. [8] displaced conventional generators by PV in a nine-bus model and found that the transient stability may be negatively affected by PV due to reduced inertia and higher generator reactance. This study also showed that the impact will be more serious if PV plants are simultaneously disconnected due to low voltage caused by disturbances. Ref. [9] utilized the IEEE 39-bus New England system to study the impact of PV on transient stability. Conducting small signal stability analysis and transient simulations, this study found that the factors pertaining to the detrimental or beneficial impact of PV on transient stability were the unit commitment and dispatch, and the protection/control strategy of PV during voltage swell or dip. Ref. [10] studied the impact of PV on a nine-bus system and found that PV generation deteriorates the stability of the system, while the P-V control mode of PV generation is better for transient stability compared with the P-Q control mode. Ref. [11] adopted the New England-New York test system and found that the integration of PV increases the angular separation of synchronous generators.

Although some studies have investigated some basic impact factors of PV generation to transient stability, the understanding of high PV generation on actual power systems is still unclear due to the complexity and non-linearity of PV control's interaction with power system electro-mechanic dynamics. This paper studied the impact of up to 80% renewable penetration in terms of instantaneous power (with 65% PV instantaneous power) on the U.S. Electric Reliability Council of Texas (ERCOT) system model. Section 2 describes the high PV models of the ERCOT system. Section 3 presents the study results of high PV's impact on transient stability. The conclusion is given in Section 4.

2. Model Overview

In a previous work supported by U.S. Department of Energy Solar Energy Technologies Office [12-18], the high PV cases for the ERCOT system were developed in PSS®E for 5%, 25%, 45%, and 65% PV with 15% wind. The high PV cases were developed by replacing conventional synchronous generators with PV power plants, with a sequence of replacement starting from coal power plants, then gas power plants, and further nuclear power plants.

The model preserves general power flow information of a summer-peak snapshot of the ERCOT system, whereas the dynamics of generators are modelled using generic machine models and parameters. The system consists of 6,102 buses and 690 generation units. The frequency response of the base model was validated using several frequency events of ERCOT recorded in GridEye [13]. The total load is 74 GW. The inertia of the base case system is $2.2 \times 10^5 \text{MVA} \cdot \text{s}$.

PV power plants are modelled by the GE Solar PV dynamic model in PSS®E [19]. PV applies volt/Var control and the plant-level supervisory control called GE SolarControl function. GE SolarControl defines a power factor range that determines real power levels at which control provides reactive power priority over real power. In addition, PV power plants are assumed to have enough fault ride through capacities that keep them online during faults.

3. Impact of PV Penetration on Transient Stability

A. Critical Clearing Time with Slight PV Increase

To study the impact of increasing PV penetration, conventional synchronous generators on the ERCOT system model are gradually replaced by PV penetration. Three synchronous generators are replaced by PV power plants in steps, replacing one generator in each step. To monitor the effect of PV on transient stability, the W4 generation unit on bus 80411 (with a 25.5 MW capacity) was replaced with a PV generation unit of the same capacity. A dynamic simulation was run for 1 second, and then a fault was applied at bus 8958, three buses away from the PV bus. The rotor angle was observed at bus 80411 to determine the critical clearing time (CCT). This was done for the base case with no PV, and then repeated as each machine was transformed to PV. The PV generators were on bus 80411, generators W4 (24 MW), W2 (25.5 MW), and W3 (24 MW), respectively.

Fig. 1-3 show the rotor angle when there was only one PV generator and the fault was cleared after 0.32 s, 0.33 s, and 0.34 s, respectively. When the fault is applied, the rotor angle is disturbed. If the rotor angle settles, then the case is stable. If the rotor angle diverges, then the case is unstable. The flat lines in Fig. 1-3 represent a state variable in the PV generation dynamic model, which keeps a constant value during the fault and therefore is ignorable. It can be observed from Fig. 1-3 that the addition of the PV generator slightly improves transient stability, since the CCT for the base case is 0.32 s, and the CCT for the case with the PV generator is 0.33 s. This can be seen by the “no PV” line diverging in Fig. 2 and then the “PV” line diverging in Fig. 3.

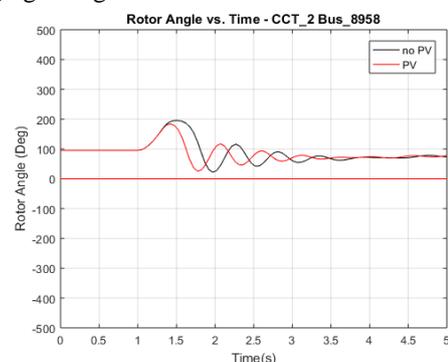


Fig. 1. Rotor angle when fault cleared after 0.32 s.

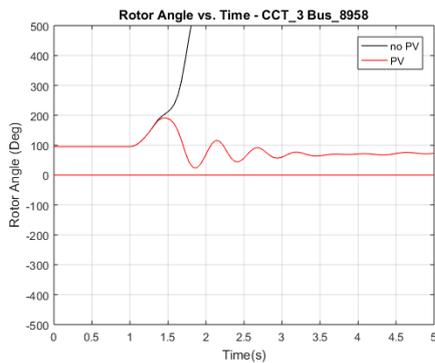


Fig. 2. Rotor angle when fault cleared after 0.33 s.

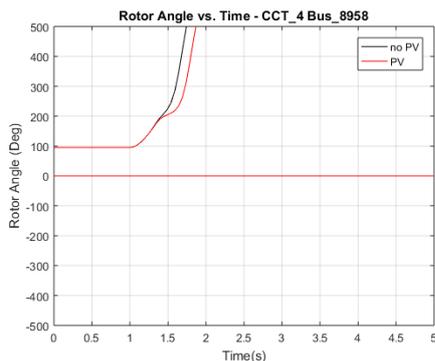


Fig. 3. Rotor angle when fault cleared after 0.34 s.

A second PV generator was then added to bus 80411 and the simulation was run again. It was found that the CCT with two PV generators becomes 0.37 s, which is a further improvement from the CCT with one PV generator added.

To test further, a third generator was replaced with a PV generator and the simulation was run another time. The CCT with three generators replaced with PV generators was found to be 0.44 s.

Next the voltage was compared for the different cases at the CCT of the base case: 0.32 s. This is shown in Fig. 4. It can be seen that as PV is added, the voltage level decreases more during the fault, but the voltage recovers more quickly.

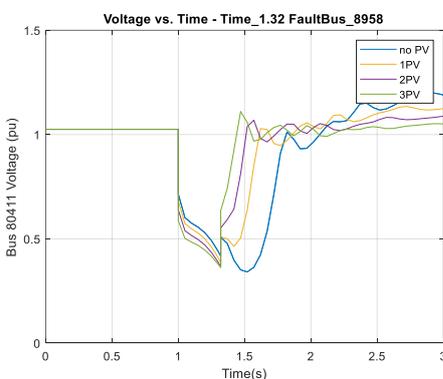


Fig. 4. Bus 80411 voltage for different amounts of PV generators.

Although the voltage level during the fault decreases as PV increases due to limited reactive power current, which results in faster rotor speed acceleration and smaller CCT, the fast voltage regulation of PV inverters can recover voltage more quickly compared with conventional

synchronous generators after faults, leading to CCT increase. From the results, it can be seen the fast voltage recovery has a larger impact when PV generators increase in a local area.

B. Critical Clearing Time with Varying Percentages of PV

Once the stability was tested with a few PV generators, it was then tested for five different percentages of renewables in the ERCOT system (5%, 25%, 45%, and 65% PV with 15% wind each, and the base case without PV and wind power). A fault was applied to a bus on the system and the rotor angles were plotted to determine the CCT. The rotor angles on buses that contained only synchronous generators for the 80% renewable case were plotted for all of the cases, so they could all be compared equally. The fault was first applied at bus 240, and then later the same test was run with the fault applied at bus 970 to confirm that the results would be similar with the fault on a different bus. To better view the results, the change in rotor angle was also plotted.

For the base case, with the fault on bus 240 the CCT was 0.25 s, and with the fault on bus 970 the CCT was 0.38 s. Fig. 5-6 show the rotor angle for when the fault on bus 240 was cleared at 0.25 s after the fault and at 0.26 s, respectively. In Fig. 6 it is clear that the rotor angle diverges and therefore the system becomes unstable.

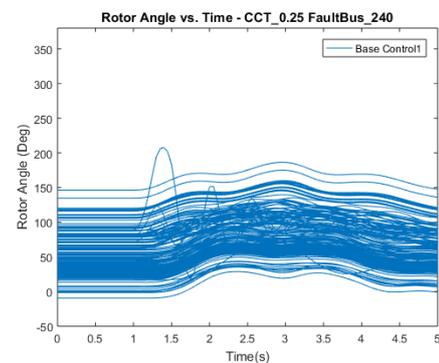


Fig. 5. Rotor angles when fault on bus 240 cleared at 0.25 s.

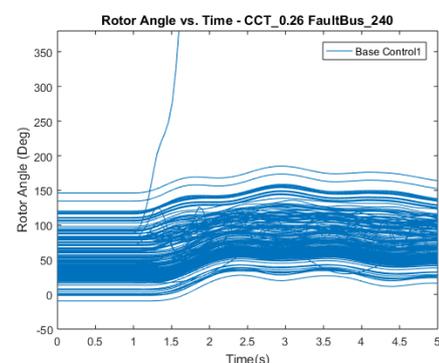


Fig. 6. Rotor angles when fault on bus 240 cleared at 0.26 s.

For the 20% renewable case (5% PV + 15% wind), with the fault on bus 240 the CCT was 0.25 s, and with the fault on bus 970 the CCT was 0.41 s. With the fault on bus 240, the CCT remained the same as the base case. With the fault

on bus 970, the CCT increased slightly with the increase in PV.

For the 40% renewable case (25% PV + 15% wind), with the fault on bus 240 the CCT was 0.25 s, and with the fault on bus 970 the CCT was 0.39 s. With the fault on bus 240, the CCT remained the same. With the fault on bus 970, the CCT decreased slightly from the 20% renewable case with the increase in PV, although still an increased CCT from the base case.

For the 60% renewable case (45% PV + 15% wind), with the fault on bus 240 the CCT was 0.25 s, and with the fault on bus 970 the CCT was 0.31 s. With the fault on bus 240, the CCT remained the same. With the fault on bus 970, the CCT decreased by a tenth of a second from the 40% renewable case. This decrease also meant a CCT below that of the base case.

For the 80% renewable case (65% PV + 15% wind), with the fault on bus 240 the CCT was 0.01 s, and with the fault on bus 970 the CCT was 0.115 s. For both cases, the CCT decreased significantly.

The CCT results were then graphed, and those results are shown in Fig. 7-8. From these results it was determined that more buses should be faulted to test if similar results would be achieved.

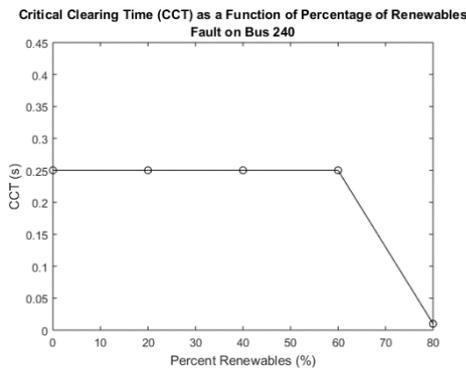


Fig. 7. CCTs for fault on bus 240.

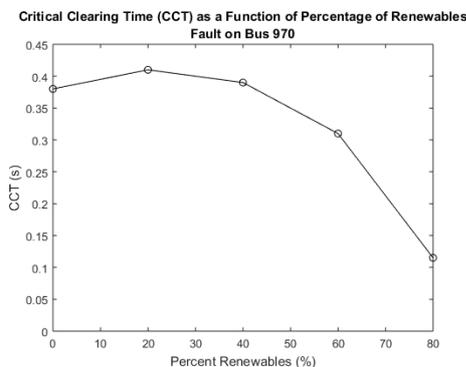


Fig. 8. CCTs for fault on bus 970.

The CCT was then tested for faulting each bus 230 kV and above. The results were similar to faulting buses 240 and 970, and a couple more examples are given in Fig. 9-10, showing buses 1685 and 3109 faulted, respectively. From these we can see that while the transient stability is sometimes slightly improved by added PV, by the time the

system has reached higher levels such as 60% and 80% renewables the transient stability is much worse.

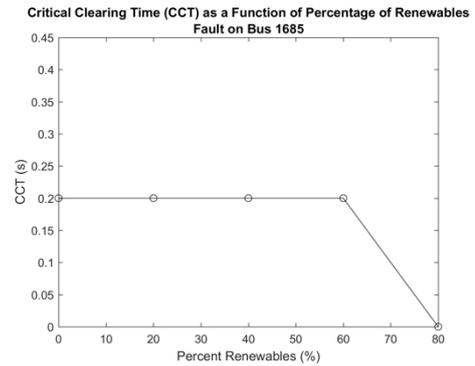


Fig. 9. CCTs for fault on bus 1685.

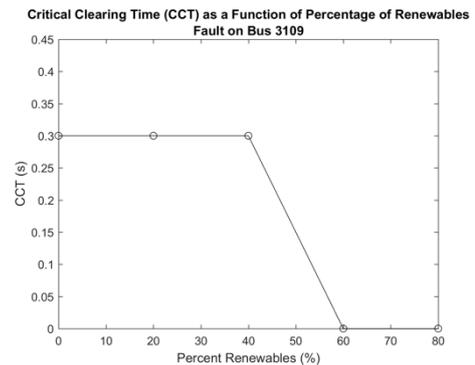


Fig. 10. CCTs for fault on bus 3109.

C. Visualization of Critical Clearing Time for the ERCOT System

To better understand the impact of PV generation on overall transient stability of the ERCOT system, the CCTs of multiple high voltage buses were simulated. A color map of the ERCOT system was then created testing the CCT for faulting each bus 230 kV and above. The maps were created for each renewable case: 0%, 20%, 40%, 60%, and 80%. Fig. 11-15 contain the maps for each renewable case. The colors represent the CCT when the bus in that part of the ERCOT system is faulted. The CCT value for each faulted bus is mapped to its color using the color bar to the right of each map. For a CCT of 0, the case did not converge.

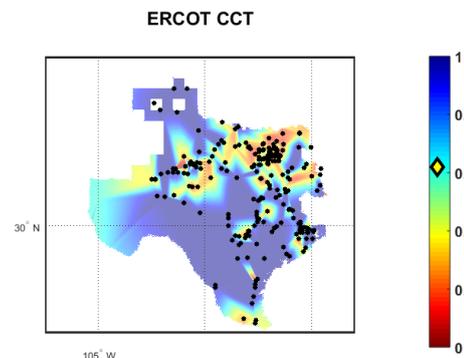


Fig. 11. Base case CCT map.

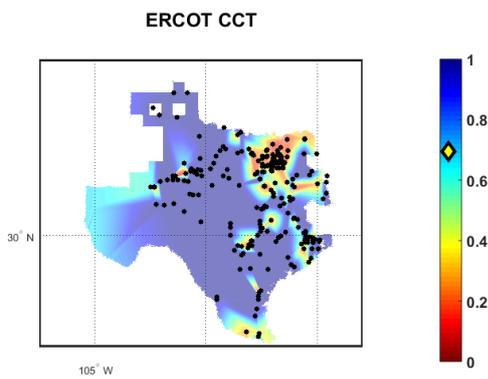


Fig. 12. 20% renewables CCT map.

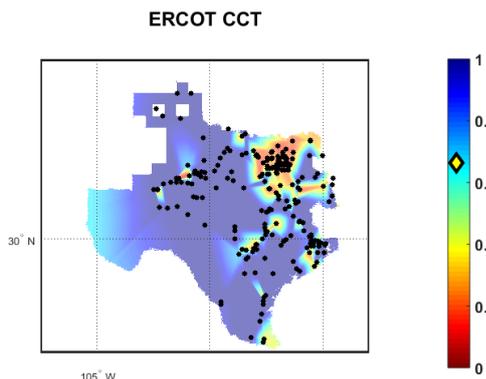


Fig. 13. 40% renewables CCT map.

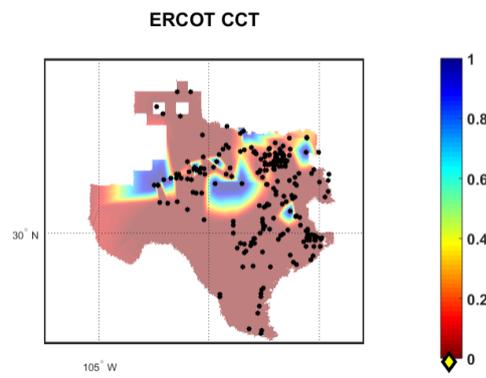


Fig. 14. 60% renewables CCT map.

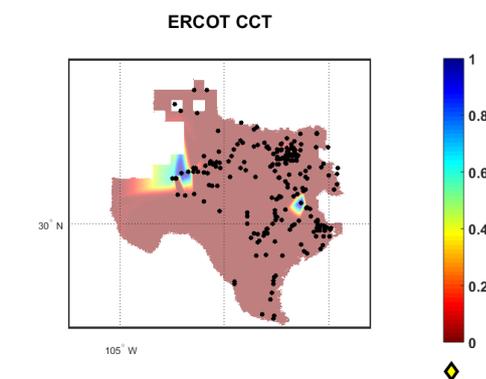


Fig. 15. 80% renewables CCT map.

As can be seen from Fig. 11-15, the effect on the CCT of adding PV increases sharply between 40% and 60%. The difference between the 40%-60% renewable cases were then investigated to determine what caused the CCT to decrease so significantly for most areas. The cases were

broken down further to 45%, 50%, and 55% renewables. The 50% and 55% renewables cases were similar to the 40% and 60% cases, respectively.

There was a difference of 13 generators between the 50% and 55% renewables cases. To further investigate at what point the CCT decreased, these generators were then changed to PV one at a time to determine the effect on the CCT. It was found that when the renewable percentage reached 54.2% that the CCT was affected significantly, as shown in Fig. 16-17. It was further found, however, that if different generators were replaced by PV, it was possible to reach a renewable percentage of 56.3% before the CCT was affected significantly.

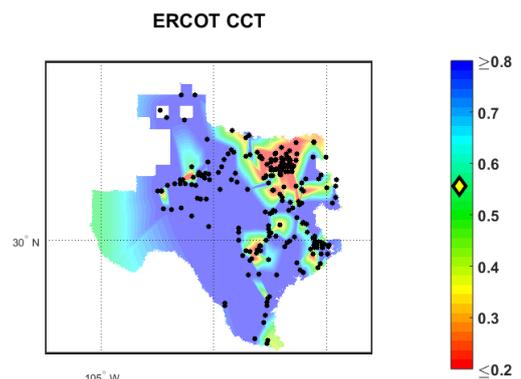


Fig. 16. 53.8% renewable CCT map.

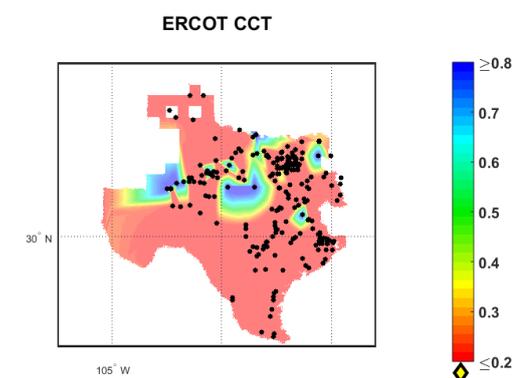


Fig. 17. 54.2% renewable CCT map.

This result shows that the impact of PV on ERCOT system frequency stability is non-linear. The incorporation of high PV penetration at the system level will fundamentally change the transient stability of a large-scale system and make the system very vulnerable to transient stability issues after a certain PV penetration point. In addition, simulation experience on model numerical convergence suggests that at high renewable penetration levels, static and dynamic reactive devices may be needed to deploy across the system, specifically, synchronous condensers in areas with low system strength. This phenomenon is also observed in other studies [20].

4. Conclusion

This study was performed to assess the impact of PV on transient stability of the ERCOT system. Study results show that under the volt/Var PV control and the plant level supervisory control (i.e. GE SolarControl) strategy, when

adding just a few PV generators for the ERCOT system, adding the PV generators slightly improves stability of the system. For the system-level high renewables penetration scenarios developed in this hypothetical ERCOT system, when adding considerable amounts of renewables the stability may hold steady up to approximately 39% PV with 15% wind, after which the CCT drops considerably or the case does not converge which is indicated as zero CCT. These results reveal the highly nonlinearity of the impact of PV generation on transient stability.

In the future, the cause of divergence and instability will be investigated, to better assess how to determine the point of instability for other systems or under different operating conditions.

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