

Algorithm optimization for PWM signal generation with selective harmonic elimination using the Walsh transform

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Abstract. The use of the Walsh transform in DC-AC PWM waveform generation allows the calculation of the switching angles by means of linear equations dependent on the fundamental amplitude.

After the description of the mathematical method used to find the solutions, it is presented a method to reduce the computation time needed to find all the switching intervals that give a useful range variation of the fundamental amplitude.

Key words

Algorithm optimisation, PWM inverters, Selective harmonic elimination, DC-AC conversion, Walsh transform.

1. Introduction

It is well known that programmed harmonic reduction in DC-AC PWM waveforms needs for the solving of non linear equations that made its application difficult in real time control of the fundamental amplitude. In these cases, a common choice is the off-line calculation of the switching angles, which establishes a dilemma between the desired precision and the memory capacity needed.

The use of the Walsh functions [1] is a mean for the linearization of the equation set that lead to the harmonic cancellation that permits the on-line calculation of the switching angles as a linear function of the fundamental amplitude [2] [3]. With this technique the use of M angles per quarter of period permits the cancellation of M-1 harmonics and the regulation of the fundamental amplitude.

Harmonic reduction in PWM DC-AC converters using the Walsh transform has been studied by the authors, in previous published works, in different aspects: method description [4], non idealities of the switching pulses [5], computation of the harmonic distortion [6] and evaluation of active and reactive power [7]. In those

works, it has been developed a method that allows the calculation of the switching angles as linear equations dependent on the fundamental amplitude.

However, this technique has the drawback of obtaining a great number of solutions that difficult the selection process of the better cases and also increments the computation time, especially when a big number of switching intervals is used.

Figure 1 shows the harmonic amplitudes of the PWM waveforms for all the intervals with solution for 4 switching angles for a quarter period, with a fundamental amplitude regulation above 20%. It is considered the medium value of the fundamental amplitude (A_1) range available for each interval vector.

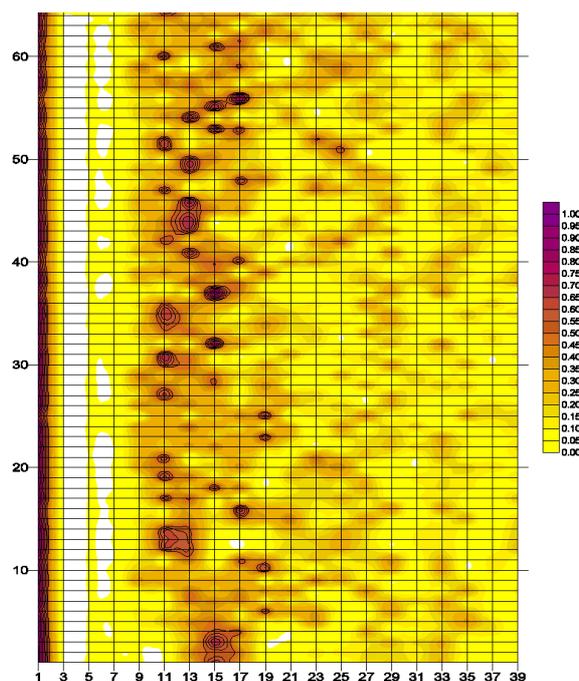


Fig. 1. Harmonic distribution for intervals with A_1 range above 20%. X axis: Order of harmonic, Y axis: Interval vector

This representation helps in the analysis of the obtained results, since easily allows the determination of those interval vectors with a better harmonic reduction. The chosen order is the increasing value of the distortion factor (DF), defined as (1).

$$DF = \frac{I}{A_1} \left(\sum_{k=3}^{39} \left(\frac{A_k}{k} \right)^2 \right)^{1/2} \quad (1)$$

From the solutions shown in figure 1, there have been chosen two cases corresponding to switching intervals $\mathbf{m}=[2 \ 7 \ 10 \ 14]$ and $\mathbf{m}=[1 \ 5 \ 10 \ 12]$, in order to compare the differences in the harmonic distribution. Both cases have been simulated in Matlab, with a value of normalized fundamental amplitude of 80%, using a power supply of 100 (V) DC and a frequency of 50 (Hz) for the bipolar PWM signals. Figures 2 and 3 show the obtained results from the simulation.

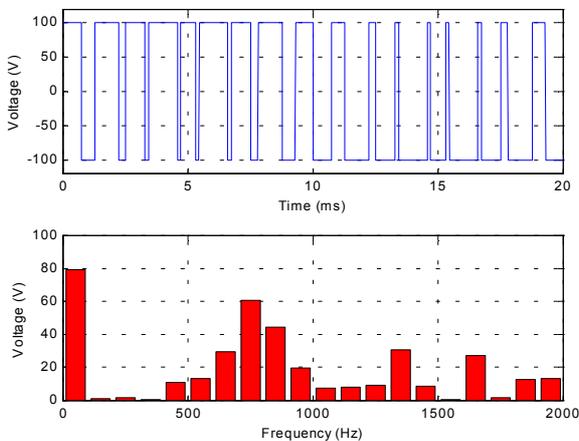


Fig. 2. PWM signal and harmonic distribution. $\mathbf{m}=[2 \ 7 \ 10 \ 14]$

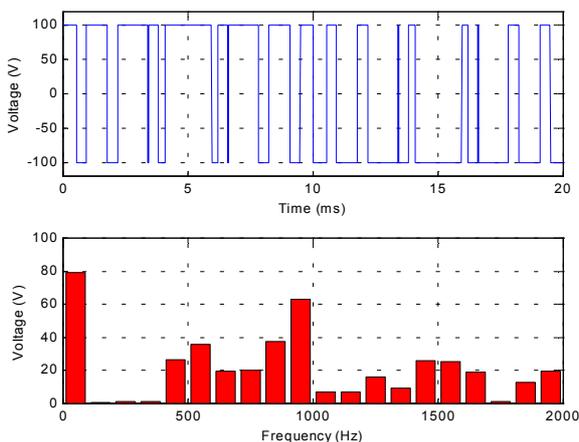


Fig. 3. PWM signal and harmonic distribution, $\mathbf{m}=[1 \ 5 \ 10 \ 12]$

The distortion factors obtained for the signals in figures 2 and 3 are 7.5% and 8.2%, respectively. Although the difference in the distortion factor is small, the differences in the harmonic distribution are more noticeable. In both cases it can be seen that the 3rd, 5th and 7th order harmonics are cancelled. This comparison shows the need of obtaining a great number of solutions in order to choose the cases that allow a minimal distortion factor or an harmonic distribution more suited to the application

(for instance, in some applications it would be more interesting that the maximum amplitudes appear in the greater order harmonics).

In the present paper it has been developed a faster algorithm that improves both the computation time and the selection criteria of the solutions in order to reduce the PWM harmonic content.

2. Method analysis

Since the problem of harmonic elimination is inherent to the frequency domain, the analysis requires the availability of reciprocal conversion tools between Walsh and Fourier transforms. The relationship between Fourier and Walsh coefficients is the starting point to compute the switching angles of the PWM waveform and can be expressed by the transformation (2) [8], where G_F and G_W are the Fourier and Walsh coefficients corresponding to the expansion of the PWM signal.

$$G_F = B G_W \quad (2)$$

The Walsh coefficients are obtained as follows:

$$G_W = C \delta + D \quad (3)$$

where $\delta = [\delta_1 \ \delta_2 \ \dots \ \delta_M]^T$ is the vector of switching angle fractions, each one referred to the beginning of its switching interval. $\delta_i \in (0,1)$.

Each quarter period is subdivided in N intervals, from 0 to N-1, but only M of which include one, and only one, switching angle. Those intervals, $m(\delta_i)$, form the elements of the switching interval vector (4).

$$\mathbf{m} = [m(\delta_1) \ m(\delta_2) \ \dots \ m(\delta_M)] \quad (4)$$

To simplify the notation the elements of vector \mathbf{m} would be referred as follows:

$$\mathbf{m} = [m(1) \ m(2) \ \dots \ m(M)] \quad (5)$$

The relationship between the fractions (δ_i) and the switching angles (α_i) is given by (6) and is represented in figure 4.

$$\alpha_i = \frac{\pi}{2N} (m(i) + \delta_i) \quad (6)$$

Fixing N as the power of 2 greater or equal to 4 times the number of angles, it can be made that all Walsh functions used in the expansion of the PWM signal have a constant value in each subinterval, reducing the complexity of the algorithm. Another simplification can be obtained fixing the end of the switching in the next interval if the value of $m(i)$ is less than $(N/2)-1$, and in the same interval otherwise.

Figure 4 shows the first quarter of a PWM signal with two switching angles (α_1, α_2) at intervals 2 and 6. In this case: $M=2, N=8, m(1)=2$ and $m(2)=6$.

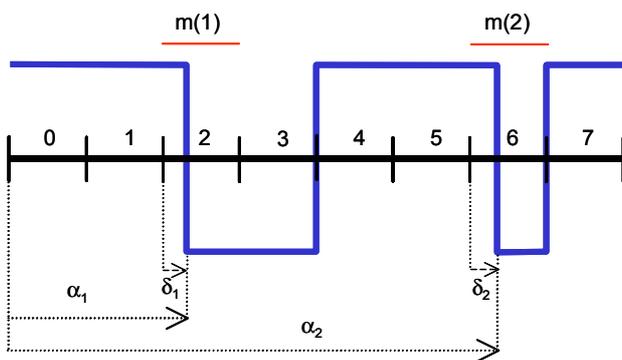


Fig. 4. PWM signal with two switching angles

Taking this into account, matrix **C** and column vector **D** are easily derived from the Walsh matrix (**W**) whose elements are obtained from (7):

$$W_{i,j} = wal(4i-3, \frac{j-1}{N}) \quad i, j = 1 \dots N \quad (7)$$

Matrix **C** is formed with the **M** columns of **W** corresponding to vector **m**, multiplied by the factor $2/N$.

$$C_{i,j} = \frac{2}{N} W_{i, m(j)+1} \quad i = 1 \dots N, j = 1 \dots M \quad (8)$$

The **N** dimension column vector **D** is obtained by (9), that makes the base for the application of the algorithm used in this paper.

$$D_i = \frac{2}{N} \left[\frac{1}{2} \sum_{j=1}^N W_{i,j} - \sum_{j=1}^M W_{i, m(j)+1} - \sum_{j=1}^M \varepsilon_j W_{i, m(j)+2} \right] \quad (9)$$

The parameter ε_j takes the value 1 if $m(j)$ is less than $(N/2)-1$ and 0 otherwise.

3. Obtained results

In order to reduce the computational time, the authors have done a study of the distribution of the switching intervals for 3 to 8 angles.

As an example, the results obtained for 4 and 8 switching angles are depicted in tables I and II, where the more frequent intervals are highlighted.

TABLE I. Distribution of switching intervals (4angles)

SWITCHING INTERVALS DISTRIBUTION								
Combinations with A1 range above 20%					All combinations			
Interval	m(1)	m(2)	m(3)	m(4)	m(1)	m(2)	m(3)	m(4)
0	2				21			
1	21				53			
2	15				65			
3	26				47	6		
4		3				44		
5		10				21		
6		16				25		
7		19				54	8	
8		10	2			22	28	
9		6	10			14	34	2
10			21				51	12
11			22				38	22
12			9	5			18	35
13				23			7	38
14				18			2	36
15				18				41
Totals	64	64	64	64	186	186	186	186

TABLE II. Distribution of switching intervals (8angles)

SWITCHING INTERVALS DISTRIBUTION																
Combinations with A1 range above 20%								All combinations								
Interval	m(1)	m(2)	m(3)	m(4)	m(5)	m(6)	m(7)	m(8)	m(1)	m(2)	m(3)	m(4)	m(5)	m(6)	m(7)	m(8)
0	91								2284							
1	820								6779							
2	1353								8869	119						
3	294	17							2642	1311						
4		338								3677						
5		913								8254	126					
6		1004								6335	660					
7		286	6							878	1208					
8			194								1501	1				
9			491								4588	23				
10			587								3976	472				
11			994	1							7246	426				
12			286	22							1256	1687				
13				184							13	1425	3			
14				338								1642	12			
15				947								7089	575			
16				720	95							3802	2207	30		
17				346	376							2366	3277	310		
18					752							1432	4628	841	13	
19					965	45						201	5106	2042	82	
20					350	254						8	3308	3440	366	
21					20	726							1036	4269	763	
22						691	21						282	3547	1712	46
23						571	58						110	2691	2167	305
24						231	275						30	1718	2643	550
25						40	592							913	3219	775
26							707							554	3654	1199
27							654							207	3672	2246
28							237	246						12	1674	4202
29							14	848							443	3732
30								760							166	3703
31								704								3816
Totals	2558	2558	2558	2558	2558	2558	2558	2558	20574	20574	20574	20574	20574	20574	20574	20574

TABLE III. Reduced switching interval range

angles	m(1)		m(2)		m(3)		m(4)		m(5)		m(6)		m(7)		m(8)		
	min	max															
3	0	6	4	10	9	15											
4	0	4	3	7	7	11	11	15									
5	0	7	5	12	11	18	18	25	24	31							
6	0	6	4	10	9	15	15	21	20	26	25	31					
7	0	5	3	8	8	13	12	17	17	22	21	26	26	31			
8	0	4	3	7	7	11	11	15	15	19	19	23	23	27	27	31	

In table I, values are shown for the 64 combinations with a fundamental amplitude range above 20% and for the 186 combinations with solution. It can be observed that each switching interval, $m(i)$, takes values around their nearest quarter, that is: $m(1)=0\dots3$, $m(2)=4\dots7$, $m(3)=8\dots11$ and $m(4)=12\dots15$.

This property is also present in the values shown in table II. In this case, the total number of combinations with solution is 20574, where 2558 of which have an amplitude range above 20%. Those distributions have been taken into account to reduce the number of iterations of the algorithm. The range for each switching interval is shown in table III.

Using these values, the processing times are drastically reduced. Figure 5 compares the differences in computational time between the use of all possible interval combinations or the reduced combinations of intervals derived from the values shown on table III.

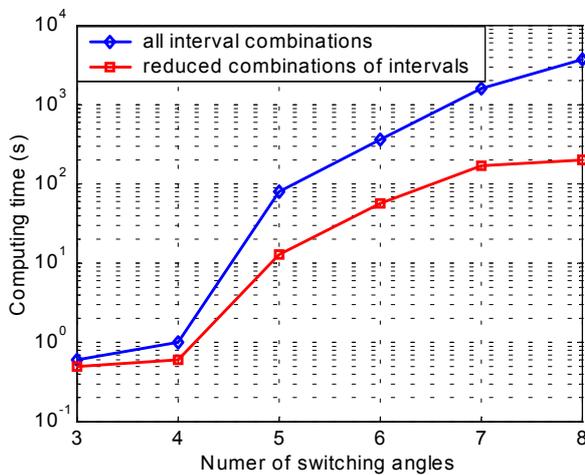


Fig. 5. Computing time comparison

The program was set up in Matlab 5.3 and the processor used was a Pentium 3 at 1.2 GHz. For comparison, figure 6 depicts the number of interval combinations obtained in each case.

4. Conclusions

It has been developed an algorithm that reduces the computation time of the PWM switching angles using the Walsh transform. The rate of time reduction varies from

1.2 for 3 switching angles to 18.3 for 8 angles, whereas the rate of number of combinations reduction varies from 1.2 for 3 switching angles to 3.2 for 8 switching angles. This shows that the method increases its benefits as increases the number of switching angles.

This method will make possible the study of a bigger number of switching angles that otherwise would have need days of processor time.

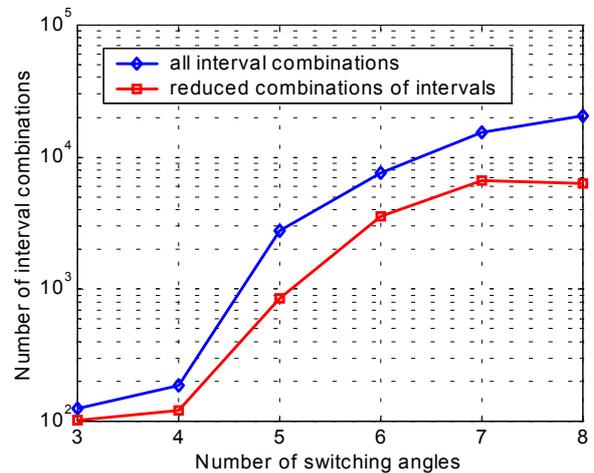


Fig. 6. Comparison of number of interval combinations

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